

# Problem-Set 09

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## Exercises

Ex. 1

Ex. 2

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## Problems

Prob. 1

a

Consider

$$\begin{aligned}A &= \{1, 2\} \\S &= \{1, 50\} \\V &= \{2, 50\} \\B &= 50\end{aligned}$$

Observe the optimal solution is  $C = 50$  while  $Alg1$  is of value  $C^* = 2$ . Therefore the approximation ratio is  $2/50 = 1/25$ .

It is easy to see the number 50 can be set arbitrarily larger, and therefore we can reach the desired unbounded approximation ratio.

b

We follow the same convention of assuming the given indices order follow non-increasing order of their densities.

For the first index  $i$  such that  $\sum_{j=1}^i v_j > B$ , denote items up to  $i-1$  by *Max-Dens-Items* and  $i$ th item by *First-Overweight*. For item  $a_i$  denote  $D(a_i)$  to be the density of  $a_i$ , i.e the *value* per one unit of *weight*.

Take  $D(\text{First-Overweight})$  and multiply it by the slack weight in  $B$  after consuming weights of *Max-Dens-Items*. Sum the resulting value along values of *Max-Dens-Items* and let  $V_{maxDensities}$  denote that sum.

It is very clear  $C^* \leq V_{maxDensities}$  as we fully utilized the space of  $B$  with maximum possible densities.

Let's return to  $Alg2$  and note how similar it is to the way we defined  $V_{maxDensities}$ . Remark that  $C = \max\{V_{maxDensities}, \text{value of First-Overweight}\}$ . We have two cases:

- Case 1. Weights of *Max-Dens-Items*  $\geq \frac{B}{2}$ .  
Then  $C \geq \frac{V_{maxDensities}}{2}$ , As *Max-Dens-Items* accounts for more than 50% of  $V_{maxDensities}$ .
- Case 2. Weights of *Max-Dens-Items*  $< \frac{B}{2}$ .  
Then the weight of *First-Overweight* is greater than  $\frac{B}{2}$ . It follows  $V_{maxDensities}$  is contributed only by *Max-Dens-Items* and *First-Overweight*. Observe one of them must contribute at least 50% of  $V_{maxDensities}$ . By definition, that one shall be selected by *Alg2*, and therefore  $C \geq \frac{V_{maxDensities}}{2}$ .

**c**

That is a standard dynamic programming problem whose solution can be found in any textbook. For brevity we only show the recurrence relation.

Base:  $S_{1,v} = w(a_1)$  if  $w(a_1) = v$ .

Induction Step:  $S_{i,v} = \min\{S_{i-1,v}, w(a_i) + S_{i-1,v-v_i}\}$

**d**

**Polynomial Time Complexity.** Observe the time complexity of *Alg3* is  $\mathcal{O}(n^2V)$ , As the memoization table is:

value\items	1	..	n
1			
..			
nV			

Since *Alg4* basically runs *Alg3* with additional linear operations, Its time complexity is  $\mathcal{O}(n^2V')$ , where  $V'$  is similarly defined but on scaled values  $v'_i$ .

Clearly  $V' = \lfloor \frac{V}{\epsilon} \cdot \frac{n}{\epsilon} \rfloor = \lfloor \frac{n}{\epsilon} \rfloor$ . So complexity of *Alg4* can be re-written as  $\mathcal{O}(n^3 \cdot \frac{1}{\epsilon})$ .

**Approximation Scheme.** The idea is to use the bound of **b** but on scaled values  $v'_i$ , then reverse the scaling to reach the intended ratio.

Let  $U$  be the upper-bound of optimal solutions which we defined earlier in **b** on given values  $v_i$ . Let  $U'$  be similarly defined but on scaled values  $v'_i$ . Define function  $f$  so that it scales value as mentioned by the author. Let  $C$  and  $C'$  denote the value of the subset solution obtained by *Alg4* but on given and scaled values respectively.

From **b**, We know there exists a solution on scaled values  $v'_i$  whose approximation ratio is 2, out of  $U'$ . Then trivially the optimal solution also can deviate by a ratio of at most 2 out of  $U'$ .

Observe if we scaled back a value then the calculated value is no greater than the original given value, since we are taking ceils. In other words,  $f^{-1}(v'_i) \leq v_i$ .

Joining all these remarks:

$$C' \geq \frac{1}{2}U'$$
$$C \geq f^{-1}(C') \geq \frac{1}{2}f^{-1}(U') = U$$

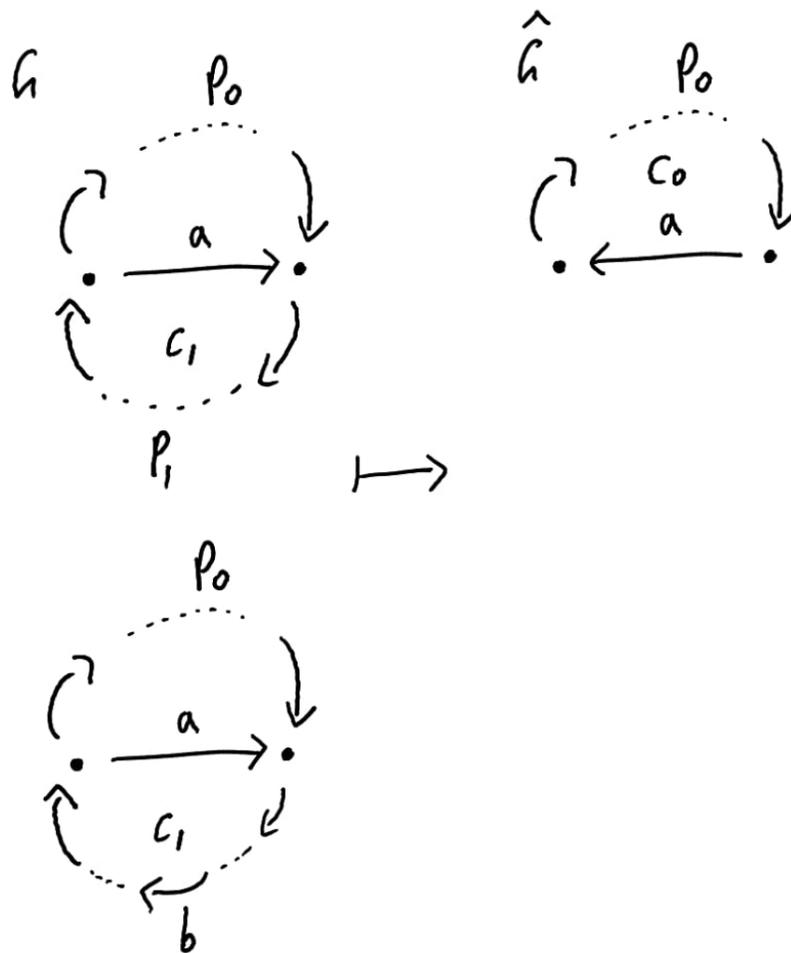
From **b**, That suffices to concluding *Alg4* is an approximation scheme.

## Prob. 2

**a**

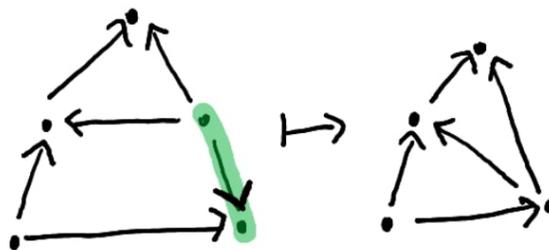
Assume for the sake of contradiction there is a cycle  $c_0$  in the reversed graph  $\hat{G}$ . Then it must contain an edge from  $A$ . Otherwise  $c_0$  would also be in graph  $G$  and by definition it must contain an edge from  $A$ . Call that edge  $a$ . Returning to  $G$ ,  $a$  would be reversed as in the figure below. It is possible to have edges other than  $a$  in cycle  $c_0$  which would also be reversed in graph  $G$ . In this case  $p_0$  would be constructed by taking the corresponding sub-cycles into it.

Since  $A$  is minimal there must be a cycle  $c_1$  in graph  $G$  which would not be covered if not for  $a$ . Observe we have cycle  $c_2$  constructed by paths  $p_0$  and  $p_1$ . What covers  $c_2$  in  $G$ ? Clearly no edge in path  $p_0$  would do that since we already considered all edges of  $A$  we might encounter and took a sub-cycle avoiding them. Then  $c_2$  is covered by edge  $b$  in path  $p_1$  which is part of the cycle  $c_1$ . That contradicts  $c_1$  being a cycle only covered by edge  $a$ . **QED**.



b

Remove all isolated vertices as they are irrelevant to cycles. Iteratively *contract* edges if they are not a side of a triangle as in the following figure.



By definition, Each edge of the resulting graph is a side of a triangle. Observe the graph is still equivalent to the previous one, When it comes to cycles. Intuitively we just condensed the length of cycles.

For a single edge  $e$ , Consider the number of different triangles it is a side of. If the number is greater than  $k$  then we must have  $e \in S$ ; Otherwise, To cover all of these triangles, We will need more than  $k$  edges. Note any two different triangles can share at most one edge. Remove edge  $e$ , and *contract* edges as needed if they are no longer a side of a triangle (suffices also to maintain no isolated vertices). Output the resulting graph as  $\hat{G}$  but with a capacity of at most  $k - 1$  edges to cover all of its cycles.

After repeating this process, We will have a graph where each edge is a side of  $k$  triangles, whose count is no more than  $k$ . Also each vertex is part of a cycle. We show now the number of vertices is upper-bounded by  $k^2 + 2k$ . The key idea is, If there is an additional vertex, We will have cycles more than what  $k$  edges can accommodate.

For a single edge  $e$ , It can cover at most  $k$  cycles. Vertices in those cycles are exactly, 2 of the edge itself, and  $k$  for each cycle. That is a total of  $2 + k$ . See the picture below:



Considering all edges of  $A$ , The total we get is  $k(2 + k) = 2k + k^2$ .

It is clear now we cannot have vertices greater than that number. As by our graph structure that vertex  $v$  would be part of a cycle, and we have already consumed the maximum number of cycles  $k$  edges can cover. In other words, We will miss a cycle which contains vertex  $v$ .

**c**

It suffices to have a polynomial-time algorithm of the kernlization procedure we illustrated.

- Degrees of vertices are computed by a linear scan of edges,  $\mathcal{O}(|E|)$ .
- Contracting edges takes at most  $\mathcal{O}(|E|^2)$ .
- Computing number of triangles for each edge takes at most  $\mathcal{O}(|E|(|E| + |V|))$  by a trivial graph search, made for each edge.
- Removing edges consumes  $\mathcal{O}(|E|)$ .

Since each step is polynomial in the size of the input, The sum of these sub-routines is polynomial also.